ZEISS Multi Sensor CMMs for Car Body Applications





ZEISS Multi Sensor CMMs for Car Body Applications More then a Robot – The Hambot

Trends in Carbody Metrology



Optical sensor for Carbody metrology	 Faster to the result. Surface information (CAD compare) Digital Twin Optical sensor on industrial robots
Multi Purpose CMMs	 Holistic Approach for measurement: More sensors in one automated Run. Increasing Flexibility: the application decides about the sensor. More Metrology in production environment. Reduction of logistics and transportation costs.
New applications due to Electric Mobility	 Short cycle times Tight tolerances Critical surfaces (machined aluminum) Access to the part

More than a Robot – The Hambot Definition Industrial Robot



Industrial robots are defined by ISO 8373:2012:

An automatically controlled, reprogrammable, multipurpose manipulator programmable in three or more axes, which can be either fixed in place or mobile for use in industrial automation applications

Classification by mechanical structure

- Linear robots (including cartesian and gantry robots)
- SCARA robots Articulated robots
- Parallel robots (delta)
- Cylindrical robots
- Others



• Horizontal arm CMMs, especially combined with optical sensors are automatically controlled, programmable in more than 3 axis and are therefore robots based on ISO 8373:2012



More than a Robot. The Hambot.

More than a Robot – The Hambot ZEISS CALENO – More than a Robot





- CALENO is a cartesian 6-axis robot
- CALENO is a is a robot with an outstanding optical sensor system EagleEye
- With CALENO you get proven CMM accuracy, a collaborative system and a multi sensor system with automatic sensor change.

This is not possible with an articulating robot.

Therefore, CALENO is more than a robot.

More than a Robot – The Hambot ZEISS CALENO – The Hambot





- The new wording Hambot combines two different needs in metrology
 - The experience with **HAM**, that it is ideal for sheet metal metrology and provides high and absolute accurate measurements
 - The requirement for high productivity, which is linked with the wording ro**bot**
- **Hambot** will be used instead of Horizontal Arm Machine to underline the new class of CMMs with optical sensors.

ZEISS Multi Sensor CMMs for Car Body Applications The Hambot - Overview

More than a Robot – The Hambot Multi-Sensor System





Multi Sensor System

- With ZEISS EagleEye, geometric elements can be measured and evaluated in record time
- Scanning of free-form geometries for CAD comparison and of geometry elements with the same sensor
- Automatic switch between optical and tactile sensors for features that cannot be optically measured.
- Thermofit extensions with up to 800mm.

Exceptional Technology - CALENO





More than a Robot – The Hambot Exceptional Technology – CALENO T





ZEISS IQS, Horizontal Arm CMMs

ZEISS Multi Sensor CMMs for Car Body Applications Safety for the operator and the Hambot

More than a Robot – The Hambot Safety for the Operator





Friction drives, lag detection and over current protection

• The multi layer safety concept will stop the system, if any obstacle is in the travel path to protect the hambot and the operator.

Safety edge at the Y-arm

 ZEISS CALENO has standard sensor strips along the entire length of both sides of the Yarm. If the narrow elastic tubes are deformed on contact, they will instantaneously shut down.



- Due to the safety features, the operator is allowed to work in the system, whilst measuring
- Risk of damaging is significantly reduced to reduce downtime and repair costs.
- Protects the operator from injury

Safety for the sensor system





Collision protection for the sensor

• The connection point to the sensor is spring-mounted on the sensor carrier. This protects the sensor from damage in the case of a collision.



Optional collision protection for the ZEISS DSC or RDS-C6

In addition, CALENO can optionally be delivered with an additional springmounted collision between the sensor carrier and the Y-arm.





Protective device on the ZEISS RST-P sensor

 Overtravel protection for ZEISS RST-P To minimize damage by collisions with the stylus. The traverse angle of the stylus on the ZEISS RST-P is an exceptionally large 26 °.

 Maximum protection of the sensor carrier and the sensor system leads to maximum availability of the system and reduced repair costs.

ZEISS Multi Sensor CMMs for Car Body Applications CALENO/CALENO T – What is new



• Column turned by 90° for enhanced stiffness

PRO/ CALENO













- New counter balance system
 - Counter weight instead of balancer
 - Less service costs
 - Improved MTBF







- New X-carrier
 - No welded dedicated X-carrier
 - Reduced complexity
 - Standard with gap covers

What is new? Summary





- CALENO is a fully new developed Hambot (horizontal arm CMM)
 - New designed X-axis as a welded structure with integrated thermal decoupling
 - New Y/Z tower with trapezoid shaped axis and linear ball bearing in all axis
 - New counterbalance system for the column
 - New full covers as standard for improved thermal isolation, environmental protection and modern design
 - New non indexing sensor carrier DSC

ZEISS Multi Sensor CMMs for Car Body Applications Articulation

Indexing sensor carrier RDS-C6 CAA





Indexing sensor carrier RDS-C6 CAA - Summary



Sensor carrier RDS-C6 CAA - Indexing articulating

probe holder

- CAA-calibration
 - For short calibration time
 - For maximum uptime of the CMM
- Step width of only 2,5°
- Position repeatability ±1"
- Maximum extension 400mm
 - For excellent accessibility even on complex parts
- Safety
 - Spring loaded probe plate with mechanical fall arrester
- Sensors
 - Touch trigger probes:
 - RST-P, TP6 und TP20
 - Optical sensor system FalconEye



More than a Robot – The Hambot Non Indexing Swivel Head DSC





Non Indexing Swivel Head DSC – Improvements CSC - DSC

ZEISS

Customer benefit

- Higher data rates for future optical sensor systems.
- Improved reliability.
- New, attractive design

Innovation

- New, improved bearings.
- Slip rings for A axis, n X 360°
- B axis ± 137,5°

Replacement for CSC and CSC-U2



More than a Robot – The Hambot Non Indexing Swivel Head DSC – Differences CSC - DSC

DSC – non indexing probe holder

- Improved performance compared to indexing swivel head
 - XYZ movement and rotation at the same time
- Improved safety, due to additional collision protection of the probe plates
- If extensions longer than 400mm are required, e.g. truck cabins
- For the optical sensor system EagleEye with6th axis
- Passive probe changer for reduced costs and improved reliability
 - Additional ports can be added
- Replaces the CSC





CSC probe changer with 4 ports

ZEISS Multi Sensor CMMs for Car Body Applications Touch Trigger Probes

Touch Trigger Probes Zeiss



RST-P Piezo Probe

- Dual principle of probing
 - first force-free Piezo probe impulse
 - then mechanical deflection
- Better reproducibility than Renishaw touch trigger probes
- Robust
 - Overtravel 26°
 - MTBF more than 5 million trigger
- Optimum universal probe due to
 - Stylus weight up to 10g
 - Stylus length up to 90mm
- Temperature stabilized invar body





Touch Trigger Probes Renishaw



TP6

- Universal probe, if customer requests Renishaw
- More over travel than TP20
- Cheapest touch trigger probe
- Trigger force can be adjusted



TP20

- Stylus modules can be changed
- Small diameter
- Different probe modules available
- Standard delivery with one module medium force and one high force
- Due to the risk of false trigger, low force should not be used





Electromechanical switch

More than a Robot – The Hambot Comparison Trigger Probes



RST-P TP6 **TP20** Electro mechanical switch Electro mechanical switch Principle of function Piezo Trigger force in the moment of data <0,01 N 0,11 - 0,3 N with stylus L=20mm 0,08N/ 0,25N/ 0,4N with stylus L=10mm capture X/Y Trigger force in the moment of data <0,01 N ?? 0,75N/ 1,9N/ 3,2N capture Z Max. possible stylus 90 mm 50 mm 50 mm (high force) length Max acceptable stylus 10 g 5 g 5 g (high force) mass Reproducibility 0,3 µm 0,35 µm 0,35 µm Stylus length at 20 mm 20 mm 10 mm specification Durability/ > 5 Mio > 1 Mio > 1 Mio no. of trigger Over travel X/Y ± 22° ± 14° $\pm 26^{\circ}$ Over travel Z 8 mm 5,5 mm 4 mm/ 3,7 mm/ 2,4 mm

ZEISS Multi Sensor CMMs for Car Body Applications Optical Sensor System EagleEye

More than a Robot – The Hambot Productivity improvement with the EagleEye system





More than a Robot – The Hambot Ease of use



- Ease of use
 - by new camera technology
 - Very high dynamic range



Without LinLog

With LinLog

– Easy scanning of different materials

Sensoreinstellungen
Belichtung
Standard Hell Dunkel
1.00



More than a Robot – The Hambot Accuracy

Sensor accuracy: 20μm¹
 System accuracy: < 70μm²





Sphere Centre Test EagleEye ●3D/µm

1 The accuracy of the sensor is defined as the maximum deviation of the X or Y center point of a sphere, measured in the measuring area of the sensor 2 Sphere center test on PRO premium 16/25. 29 angular positions of A-/ B- and C-axis

More than a Robot – The Hambot Robustness

• Mechanically robust system without moving parts

- Body out of aluminum
 - Sensor
 - C-axis



- No spikes, even at critical geometries and materials
 - Due to LinLog Technology











ZEINN

Description of the Application/ differentiation



	transformed and transformed a			
Feature Analysis	Feature Serial Measurement	CAD Compare outer shell	CAD Compare problem analysis	Complete Scan for virtual Meisterbock
Individual features are measured in order to detect and correct problems. Feature measurement during product startup.	Process control based on test features and functional dimensions. Statistical evaluation of the results. Samples from the current series.	Essentially, the visible surfaces in the area of the outer skin are detected. There is no requirement to detect the inside of the components, or the structural areas.	A typical problem analysis with optical metrology is shown in the picture above. It is e.g. for leak tests in the area of the doors. For this purpose, only the information in this subarea is needed.	All components are recorded completely, ie inside and outside, in order to carry out virtual analyzes and simulations of the components to each other. For this, the deformations must be simulated by the dead weight of the components for the virtual masterbuck.

ZEISS Multi Sensor CMMs for Car Body Applications Software

ZEISS CALIGO - The software for freeform surfaces and features





ZEISS PiWeb - Quality data management





ZEISS Multi Sensor CMMs for Car Body Applications Applications

Analysis of press parts, assemblies and BIW











In which phase is being measured?

- Part qualification for start up phase of production
- Fast analysis in the series

What will be measured?

• Press parts, hanging parts, up to the complete body-in-white.

How will be measured?

- Fast, tactile and optical feature measurement
- CAD compare for problem analysis.
- Digitization

How to create the measuring programs?

- Offline, with simulation for the start up phase
- Direct at the CMM for problem analysis

Meisterbock analysis and finished car analysis









In which phase is being measured?

- Part qualification for start up phase of production
- Fast analysis in the series

What will be measured?

- Verification of the dimension of the individual components.
- Verification and analysis of quality, flush&gap, optics, haptics, function and assemblies capability.

How will be measured?

 If necessary, tolerances, construction and design issues can be discussed on the Meisterbock with parts, data and reports

How to create the measuring programs?

• Direct at the CMM for problem analysis

More than a Robot – The Hambot Serial measurement BIW







In which phase is being measured?

• Fast process control in serial production

What will be measured?

• Body-in-white and hanging parts

How will be measured?

• Direct measurement of geometrical features with optical or tactile sensor.

How to create the measuring programs?

• Central creation of measuring programs, or at offline stations in the measuring room.

Serial measurement BIW – Correlation for Inline Measurement





In which phase is being measured?

• Correlation for inline measurement

What will be measured?

• Body-in-white and hanging parts

How will be measured?

• Direct measurement of geometrical features with optical or tactile sensor .

How to create the measuring programs?

• Central creation of measuring programs, or at offline stations in the measuring room.

ZEISS Multi Sensor CMMs for Car Body Applications Portfolio Overview

More than a Robot – The Hambot Portfolio Overview





The platform strategy





The platform strategy





	CALENO / CALENO T
Accuracy for 16/25	27+L/80≤70
Option High accuracy	18+L/125≤50
Measuring range X	3.000 - 25.000
Measuring range Y	1200 ¹ , 1600, 1800 ²
Measuring range Z	2100, 2500, 3000 ²
Max acceleration	1000mm/s ²
Option performance	1500mm/s ²
Max. Travel speed without light barrier	260mm/s
Max. Travel speed with light barrier	866mm/s ³
Sensor Carrier	RDS-C6, indexing 2,5°/
	DSC, continuous
Max. probe extension RDS (indexing)	400mm
Max. probe extension CSC (continuous)	800mm
Tactile probes	TP6/ TP20/ RST-P
Optical sensor CSC	EagleEye
Covers	Full covers

ZEISS Multi Sensor CMMs for Car Body Applications Summary



More than a Robot – The Hambot Summary

- Modular platform concept of the CALENO / CALENO For an optimized adaption of the CMM to the customer needs
 - The CMM can be upgraded with modules like high speed and high accuracy
- Flexible installation
 - Flush to floor with CALENO
 - Side mounted table version CALENO T
- Highest precision and highest productivity
- Robust and service-friendly
- RDS C6 CAA, DSC
 - the benchmark for indexing and continuous articulating heads
- Machine and operator safety
- Maximum flexibility of the measuring range
- Technology from one source: ZEISS









More than a Robot – The Hambot Solutions





CALENO RDS-C6 CAA Duplex

Typical for OEMs with small and medium quantities or pure analysis systems

- Analysis
- Process control series and correlation low and mid volume
- Meisterbock CMMs
- Finished car analysis



CALENO T Single/ Duplex

Typical for 1st Tier

- Analysis of press parts and hanging parts
- Serial measurement, e.g., battery trays in production environment



CALENO DSC Duplex

Typical for big OEMs

- Analysis
- Process control series and correlation high volume
- Meisterbock CMMs
- Finished car analysis

Hambot und Scanbox: Differentiation of the two measuring systems Inline/Atline/Offline



		Strength: Metrology Feature extraction	Strength: Digital Twin Full part scanning		
Inline 01	Measuring of individual modules and full part digitization of assembled parts and complete bodies // e.g. 54 sec.	AICell trace	ATOS Inline	Process control	Metr
Atline 02	Complete optical scans for CAD comparison e.g. of attachments // within 10 to 15 min	Hambot – CALENO	ATOS ScanBox		ology & Digital 1
Offline 0	Precise analysis of any carbody part. Highly precise and optically efficient. // from a few min. to hrs.	Hambot – CALENO	ATOS ScanBox		ſwin



Seeing beyond